

## Eigenvalues and Eigenvectors of a matrix

Let  $A$  be an  $n \times n$  matrix and  $B$  a  $n \times 1$  vector.

We say that the vector  $B$  is an *eigenvector* for the matrix  $A$  if there exists a constant  $\lambda$  (called the *eigenvalue* associated to the eigenvector  $B$ ) such that

$$A \cdot B = \lambda B$$

In other words, the requirement for  $B$  to be an eigenvector for the matrix  $A$  is that the vector  $A \cdot B$  is **proportional** to  $B$ , and the corresponding eigenvalue  $\lambda$  is the constant of proportionality.

**Examples:** Consider

$$A = \begin{bmatrix} 2 & 5 \\ 6 & 1 \end{bmatrix} \quad B = \begin{bmatrix} 5 \\ -5 \end{bmatrix} \quad C = \begin{bmatrix} 3 \\ 3 \end{bmatrix}$$

We have

$$A \cdot B = \begin{bmatrix} -15 \\ 25 \end{bmatrix}$$

This vector is not proportional to  $B$  since  $-15/5 \neq 25/-5$ . Thus  $B$  is not an eigenvector for the matrix  $A$ .

$$A \cdot C = \begin{bmatrix} 21 \\ 21 \end{bmatrix}$$

This vector is proportional to  $C$ :  $21/3 = 21/3 = 7$ , in other words  $A \cdot C = 7C$ . The corresponding eigenvalue is  $\lambda = 7$ .

Now we return to the study of populations with age structures.

Recall that the population at time  $n$  is represented by a vector

$$B_n = \begin{bmatrix} C_n \\ M_n \\ O_n \end{bmatrix}$$

which satisfies the recursive equation  $B_{n+1} = A \cdot B_n$ , where  $A$  is the transition matrix.

We will explore how the eigenvalues and eigenvectors of the transition matrix  $A$  relate to the notions of stable state for the population vector, and exponential behavior for the total population size.

Recall the definitions:

The distribution vector at step  $n$  is

$$D_n = \begin{bmatrix} C_n/P_n \\ M_n/P_n \\ O_n/P_n \end{bmatrix}$$

where  $P_n = C_n + M_n + O_n$ .

We say that the population has reached a **stable state** at step  $n$  if  $D_n = D_{n+1}$ . That is, if the distribution vector does not change when we go to the next step. The distribution vector  $D_n$  achieved when the population reaches a stable state is called the **stable distribution** of the population.

We say that the total size of the population has exponential behavior with per-capita growth rate  $r$  if  $\frac{P_{n+1}}{P_n} = 1+r$  whenever  $n$  is large enough (this means that the ratio  $\frac{P_{n+1}}{P_n} = 1+r$  stabilizes at a constant value).

**Observation:** If the population has reached stable state at step  $n$ , this means that the vector  $B_n$  is an eigenvector for the matrix  $A$ .

Indeed, stable state means that the vectors  $B_n/P_n$  and  $B_{n+1}/P_{n+1}$  coincide, where by  $B_n/P_n$  we mean the vector obtained by dividing each entry in  $B_n$  by the total population size  $P_n$ . Recalling that  $B_{n+1} = AB_n$ , this equation can be written as

$$\frac{AB_n}{P_{n+1}} = \frac{B_n}{P_n},$$

or equivalently

$$AB_n = \frac{P_{n+1}}{P_n} \cdot B_n$$

which means that  $B_n$  is an eigenvector for  $A$  with corresponding eigenvalue equal to the ratio  $P_{n+1}/P_n$ .

Typically, the transition matrix  $A$  will have three eigenvalues  $\alpha_1, \alpha_2, \alpha_3$ , and only one of these eigenvalues will be larger than 1. Say that  $\alpha_1 > 1$  and  $< -1, \alpha_2, \alpha_3 < 1$ . We will refer to  $\alpha_1$  as the **dominant eigenvalue**. Let's say that the eigenvectors corresponding to  $\alpha_1, \alpha_2, \alpha_3$  are  $U_1, U_2, U_3$  respectively so that we have  $A \cdot U_1 = \alpha_1 U_1, A \cdot U_2 = \alpha_2 U_2, A \cdot U_3 = \alpha_3 U_3$ . Further, the initial population vector  $B_0$  can usually be expressed as a linear combination of the eigenvectors:

$$B_0 = c_1 U_1 + c_2 U_2 + c_3 U_3$$

It follows that

$$\begin{aligned} B_1 &= A \cdot B_0 = A(c_1 U_1 + c_2 U_2 + c_3 U_3) = c_1(AU_1) + c_2(AU_2) + c_3(AU_3) \\ &= (c_1 \alpha_1)U_1 + (c_2 \alpha_2)U_2 + (c_3 \alpha_3)U_3 \end{aligned}$$

$$\begin{aligned} B_2 &= AB_1 = A(c_1 \alpha_1 U_1 + c_2 \alpha_2 U_2 + c_3 \alpha_3 U_3) = c_1 \alpha_1 (AU_1) + c_2 \alpha_2 (AU_2) + c_3 \alpha_3 (AU_3) \\ &= c_1 \alpha_1^2 U_1 + c_2 \alpha_2^2 U_2 + c_3 \alpha_3^2 U_3 \end{aligned}$$

and in general

$$B_n = c_1 \alpha_1^n U_1 + c_2 \alpha_2^n U_2 + c_3 \alpha_3^n U_3$$

Since  $-1 < \alpha_2, \alpha_3 < 1$ , their powers  $\alpha_2^n, \alpha_3^n$  will approach zero when  $n$  is very large, therefore the entries in  $c_2\alpha_2^n U_2 + c_3\alpha_3^n U_3$  become negligible in the long run, and we can approximate

$$B_n \cong c_1\alpha_1^n U_1 \quad \text{for } n \text{ sufficiently large}$$

This means that  $B_n$  will be an eigenvector for the transition matrix  $A$  when  $n$  is sufficiently large, and therefore we will have exponential behavior ( $P_{n+1} = \alpha_1 P_n$ ) for the total population size and stable distribution vectors from that point on.