

## Exam 2 - Solution Key

1.  $u'' + 0.25u' + 4u = 2\cos(3t)$ .

Let  $x_1 = u \quad \text{Then: } x_1' = u' = x_2$   
 $x_2 = u' \quad x_2' = u'' = -0.25u' - 4u + 2\cos(3t)$   
 $= -0.25x_2 - 4x_1 + 2\cos(3t)$

So  $\begin{pmatrix} x_1 \\ x_2 \end{pmatrix}' = \begin{pmatrix} x_2 \\ -0.25x_2 - 4x_1 + 2\cos(3t) \end{pmatrix} = \begin{pmatrix} 0 & 1 \\ -4 & -0.25 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} + \begin{pmatrix} 0 \\ 2\cos(3t) \end{pmatrix}$ .

2.  $\vec{x}' = A\vec{x}$  with  $A = \begin{bmatrix} 1 & 1 \\ 4 & -2 \end{bmatrix}$ .

$$\det(A - \lambda I) = \det \begin{bmatrix} 1-\lambda & 1 \\ 4 & -2-\lambda \end{bmatrix} = (1-\lambda)(-2-\lambda) - 4 = \lambda^2 + \lambda - 6 = (\lambda+3)(\lambda-2).$$

$$\lambda_1 = 2: (A - 2I)\vec{v} = \vec{0}: \begin{bmatrix} -1 & 1 \\ 4 & -4 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \quad \begin{array}{l} -v_1 + v_2 = 0 \\ v_1 = v_2 \end{array} \quad \therefore \vec{v}^{(1)} = \begin{bmatrix} 1 \\ 1 \end{bmatrix}.$$

$$\lambda_2 = -3: (A + 3I)\vec{v} = \vec{0}: \begin{bmatrix} 4 & 1 \\ 4 & 1 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \quad \begin{array}{l} 4v_1 + v_2 = 0 \\ v_2 = -4v_1 \end{array} \quad \therefore \vec{v}^{(2)} = \begin{bmatrix} 1 \\ -4 \end{bmatrix}$$

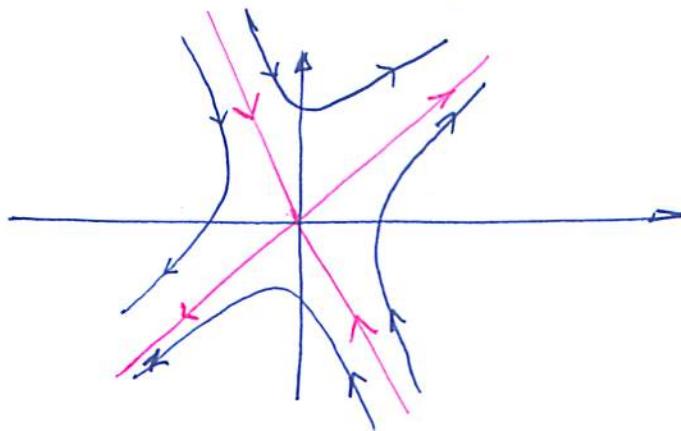
a) Fundamental solutions are:  $\vec{x}^{(1)} = \vec{v}^{(1)} e^{\lambda_1 t} = \begin{bmatrix} 1 \\ 1 \end{bmatrix} e^{2t}$   
 $\vec{x}^{(2)} = \vec{v}^{(2)} e^{\lambda_2 t} = \begin{bmatrix} 1 \\ -4 \end{bmatrix} e^{-3t}$ .

b) General solution:  $\vec{x}(t) = c_1 \vec{x}^{(1)}(t) + c_2 \vec{x}^{(2)}(t) = c_1 \begin{bmatrix} 1 \\ 1 \end{bmatrix} e^{2t} + c_2 \begin{bmatrix} 1 \\ -4 \end{bmatrix} e^{-3t}$

c) To show independence of these solutions:

$$W[\vec{x}^{(1)}, \vec{x}^{(2)}](t) = \det \begin{bmatrix} e^{2t} & e^{-3t} \\ e^{2t} & -4e^{-3t} \end{bmatrix} = -4e^{-t} - e^{-t} = -5e^{-t} \neq 0.$$

d).



3. We are given  $\lambda_1 = 2$ ,  $\vec{v}^{(1)} = \begin{bmatrix} 1 \\ 3 \end{bmatrix}$  and  $\lambda_2 = 4$ ,  $\vec{v}^{(2)} = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$ .

(a) The general solution to  $\dot{\vec{x}} = A\vec{x}$  is

$$\vec{x}(t) = c_1 \begin{bmatrix} 1 \\ 3 \end{bmatrix} e^{2t} + c_2 \begin{bmatrix} 1 \\ 1 \end{bmatrix} e^{4t}$$

$$(b) \quad \vec{x}(0) = c_1 \begin{bmatrix} 1 \\ 3 \end{bmatrix} + c_2 \begin{bmatrix} 1 \\ 1 \end{bmatrix} = \begin{bmatrix} c_1 + c_2 \\ 3c_1 + c_2 \end{bmatrix} = \begin{bmatrix} 2 \\ -1 \end{bmatrix}$$

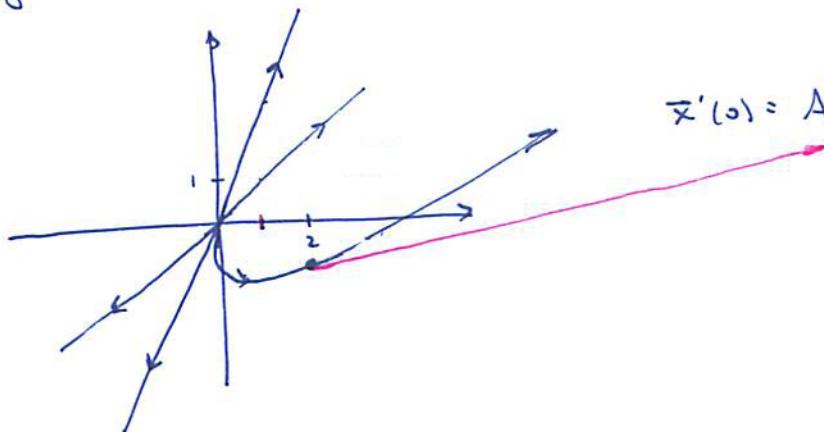
$$\begin{bmatrix} 1 & 1 \\ 3 & 1 \end{bmatrix} \begin{bmatrix} 2 \\ -1 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 1 & 2 \\ 0 & -2 & -7 \end{bmatrix} \text{ so } c_2 = \frac{-7}{-2} = \frac{7}{2}, \\ c_1 = 2 - c_2 = 2 - \frac{7}{2} = -\frac{3}{2}.$$

(c) As  $t \rightarrow \infty$ , solutions become unbounded by moving along a trajectory that eventually becomes parallel to  $\begin{bmatrix} 1 \\ 1 \end{bmatrix}$ , the eigenvector for the dominant eigenvalue.

(d) As  $t \rightarrow -\infty$ , solutions approach the origin

along a trajectory that is parallel to  $\begin{bmatrix} 1 \\ 3 \end{bmatrix}$ , the "dominant" eigenvalue when you think about  $t$  running backwards ( $t \rightarrow -\infty$ ).

(e)



$$\vec{x}'(0) = A\vec{x}(0) = \begin{bmatrix} 5 & -1 \\ 3 & 1 \end{bmatrix} \begin{bmatrix} 2 \\ -1 \end{bmatrix} = \begin{bmatrix} 11 \\ 5 \end{bmatrix}$$

$$4. A = \begin{bmatrix} 2 & -5 \\ i & -2 \end{bmatrix} \quad \lambda_1 = i, \vec{v}^{(1)} = \begin{bmatrix} 2+i \\ 1 \end{bmatrix}.$$

$$(a) A \vec{v}^{(1)} = \begin{bmatrix} 2 & -5 \\ i & -2 \end{bmatrix} \begin{bmatrix} 2+i \\ 1 \end{bmatrix} = \begin{bmatrix} 2+2i-5 \\ 2i-2 \end{bmatrix} = \begin{bmatrix} -1+2i \\ i \end{bmatrix}$$

$$\lambda_1 \vec{v}^{(1)} = i \begin{bmatrix} 2+i \\ 1 \end{bmatrix} = \begin{bmatrix} 2i-i \\ i \end{bmatrix} = \begin{bmatrix} -1+2i \\ i \end{bmatrix}$$

$$(b) \lambda_2 = \overline{\lambda}_1 = -i \quad \vec{v}^{(2)} = \overline{\vec{v}^{(1)}} = \begin{bmatrix} 2-i \\ 1 \end{bmatrix}.$$

$$(c) \vec{x} = \vec{v}^{(1)} e^{\lambda_1 t} = \begin{bmatrix} 2+i \\ 1 \end{bmatrix} e^{it} = \begin{bmatrix} 2+i \\ 1 \end{bmatrix} (\cos t + i \sin t)$$

$$= \begin{bmatrix} 2 \cos t + i \cos t + 2i \sin t - \sin t \\ \cos t + i \sin t \end{bmatrix} = \begin{bmatrix} 2 \cos t - \sin t \\ \cos t \end{bmatrix} + i \begin{bmatrix} \cos t + 2 \sin t \\ \sin t \end{bmatrix}$$

$$\therefore \vec{x}^{(1)}(t) = \begin{bmatrix} 2 \cos t - \sin t \\ \cos t \end{bmatrix}, \vec{x}^{(2)}(t) = \begin{bmatrix} \cos t + 2 \sin t \\ \sin t \end{bmatrix}$$

is a fundamental set of solutions to  $\vec{x}' = A\vec{x}$ .

(d)  $i$  can't be. This new eigenvector must be a multiple of the one we've been using up to now. To check this:

$$\begin{bmatrix} 5 \\ 2-i \end{bmatrix} = a \begin{bmatrix} 2+i \\ 1 \end{bmatrix} \text{ requires } (2 \text{ nd component}) \quad a = 2-i.$$

Checking the first component:  $(2-i)(2+i) = 4 - i^2 = 4 + 1 = 5$ .

so  $\begin{bmatrix} 5 \\ 2-i \end{bmatrix}$  is just a multiple of  $\begin{bmatrix} 2+i \\ 1 \end{bmatrix}$  which makes this eigenvector dependent on  $\vec{v}^{(1)}$ .