

## Math 532: Homework 7

(1) For each of the problems below, the function  $f(x, y)$  is defined as follows. First  $f$  rotates  $(x, y)$  about the point  $A = (1, 1)$  by  $\pi/2$ , then it takes the result and translates it by  $B = (1, 3)$ , and then it takes that result and rotates it about the point  $C = (2, 4)$  by  $\pi$ . Thus, we can view  $f$  as being  $R_{\pi, C} T_B R_{\pi/2, A}$ .

(a) Calculate  $f(2, 3)$ .

(b) Calculate  $f(3, 3)$ .

(c) Calculate  $f(4, 5)$ .

(d) Find a point  $(x, y)$  that is mapped to itself by  $f$ . In other words, find a point  $(x, y)$  such that  $f(x, y) = (x, y)$ .

(2) Show that a translation by  $(a, b)$  is equivalent to a rotation about the origin by  $\pi$  followed by a rotation about the point  $(a/2, b/2)$  by  $\pi$ .

(3) Using the information in the above problems, explain why the  $f$  in problem (1) is a rotation about some point  $D$  by  $3\pi/2$ . What are the coordinates of the point  $D$ ?

## Solutions

(1) For the problems, it helps to observe that

$$R_{\pi,C}T_B R_{\pi/2,A} = \begin{pmatrix} -1 & 0 & 4 \\ 0 & -1 & 8 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 1 \\ 0 & 1 & 3 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 0 & -1 & 2 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix} = \begin{pmatrix} 0 & 1 & 1 \\ -1 & 0 & 5 \\ 0 & 0 & 1 \end{pmatrix}.$$

Thus,

$$R_{\pi,C}T_B R_{\pi/2,A} \begin{pmatrix} x \\ y \\ 1 \end{pmatrix} = \begin{pmatrix} y + 1 \\ -x + 5 \\ 1 \end{pmatrix}.$$

We easily get then that the answer to (a) is  $(4, 3)$ , the answer to (b) is  $(4, 2)$ , and the answer to (c) is  $(6, 1)$ . For (d), we want  $x = y + 1$  and  $y = -x + 5$ . Thus, the answer to (d) is  $(x, y) = (3, 2)$ .

(2) This can be done geometrically using the information in the first example on translations and rotations. We use instead the interpretation by matrices. The result follows from

$$R_{\pi,(a/2,b/2)} R_{\pi,(0,0)} = \begin{pmatrix} -1 & 0 & a \\ 0 & -1 & b \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} -1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 1 \end{pmatrix} = \begin{pmatrix} 1 & 0 & a \\ 0 & 1 & b \\ 0 & 0 & 1 \end{pmatrix} = T_{(a,b)}.$$

(3) From (2), we can write  $f$  as a composition of 4 rotations about points by  $\pi/2$ ,  $\pi$ ,  $\pi$ , and  $\pi$ . Applying the theorem about compositions of rotations, we obtain that  $f$  is a rotation about some point  $D$  by  $3\pi/2$ . In (1) (d), we saw that  $f(3, 2) = (3, 2)$ . The only way this can occur is if  $D = (3, 2)$ .