

**MATH 550, VECTOR ANALYSIS, EXTRA
HOMEWORK 3 AND SOLUTIONS**

Problem 0. Suppose $\mathbf{a}, \mathbf{b}, \mathbf{c} \in \mathbb{R}^3$. Show that $(\mathbf{a} \times \mathbf{b}) \times \mathbf{c} = -\mathbf{a}(\mathbf{b} \cdot \mathbf{c}) + \mathbf{b}(\mathbf{a} \cdot \mathbf{c})$.

Solution: Let $\mathbf{a} = \langle a_1, a_2, a_3 \rangle$, $\mathbf{b} = \langle b_1, b_2, b_3 \rangle$, $\mathbf{c} = \langle c_1, c_2, c_3 \rangle$. Then $\mathbf{a} \times \mathbf{b} = \langle a_2b_3 - a_3b_2, a_3b_1 - a_1b_3, a_1b_2 - a_2b_1 \rangle$, and

$$\begin{aligned} & (\mathbf{a} \times \mathbf{b}) \times \mathbf{c} \\ &= \begin{pmatrix} (a_3b_1 - a_1b_3)c_3 - (a_1b_2 - a_2b_1)c_2 \\ (a_1b_2 - a_2b_1)c_1 - (a_2b_3 - a_3b_2)c_3 \\ (a_2b_3 - a_3b_2)c_2 - (a_3b_1 - a_1b_3)c_1 \end{pmatrix} = \begin{pmatrix} -a_1(b_2c_2 + b_3c_3) + b_1(a_2c_2 + a_3c_3) \\ -a_2(b_1c_1 + b_3c_3) + b_2(a_1c_1 + a_3c_3) \\ -a_3(b_1c_1 + b_2c_2) + b_3(a_1c_1 + a_2c_2) \end{pmatrix} \\ &= \begin{pmatrix} -a_1(b_1c_1 + b_2c_2 + b_3c_3) + b_1(a_1c_1 + a_2c_2 + a_3c_3) \\ -a_2(b_1c_1 + b_2c_2 + b_3c_3) + b_2(a_1c_1 + a_2c_2 + a_3c_3) \\ -a_3(b_1c_1 + b_2c_2 + b_3c_3) + b_3(a_1c_1 + a_2c_2 + a_3c_3) \end{pmatrix} \\ &= - \begin{pmatrix} a_1 \\ a_2 \\ a_3 \end{pmatrix} (b_1c_1 + b_2c_2 + b_3c_3) + \begin{pmatrix} b_1 \\ b_2 \\ b_3 \end{pmatrix} (a_1c_1 + a_2c_2 + a_3c_3) \\ &= -\mathbf{a}(\mathbf{b} \cdot \mathbf{c}) + \mathbf{b}(\mathbf{a} \cdot \mathbf{c}). \end{aligned}$$

Suppose $\hat{\mathbf{u}}$ is a unit vector in the abstract vector space V , and $\theta \in \mathbb{R}$. For every vector \mathbf{r} in V define:

$$R(\theta, \hat{\mathbf{u}})\mathbf{r} = \mathbf{r} \cos \theta + \hat{\mathbf{u}}(\hat{\mathbf{u}} \cdot \mathbf{r})(1 - \cos \theta) + \hat{\mathbf{u}} \times \mathbf{r} \sin \theta.$$

Suppose $\mathbf{v}, \mathbf{w} \in V$.

Problem 1. Show that $[R(\theta, \hat{\mathbf{u}})\mathbf{v}] \cdot [R(\theta, \hat{\mathbf{u}})\mathbf{w}] = \mathbf{v} \cdot \mathbf{w}$.

Solution: We use direct calculation:

$$\begin{aligned} & R(\theta, \hat{\mathbf{u}})\mathbf{v} \cdot R(\theta, \hat{\mathbf{u}})\mathbf{w} \\ &= [\mathbf{v} \cos \theta + \hat{\mathbf{u}}(\hat{\mathbf{u}} \cdot \mathbf{v})(1 - \cos \theta) + \hat{\mathbf{u}} \times \mathbf{v} \sin \theta] \cdot [\mathbf{w} \cos \theta + \hat{\mathbf{u}}(\hat{\mathbf{u}} \cdot \mathbf{w})(1 - \cos \theta) + \hat{\mathbf{u}} \times \mathbf{w} \sin \theta] \\ &= \mathbf{v} \cdot \mathbf{w} \cos^2 \theta + (\hat{\mathbf{u}} \cdot \mathbf{v})(\hat{\mathbf{u}} \cdot \mathbf{w}) \cos \theta (1 - \cos \theta) + \mathbf{v} \cdot \hat{\mathbf{u}} \times \mathbf{w} \cos \theta \sin \theta \\ &\quad + (\hat{\mathbf{u}} \cdot \mathbf{w})(\hat{\mathbf{u}} \cdot \mathbf{v}) \cos \theta (1 - \cos \theta) + (\hat{\mathbf{u}} \cdot \mathbf{v})(\hat{\mathbf{u}} \cdot \mathbf{w})(1 - \cos \theta)^2 \\ &\quad + \hat{\mathbf{u}} \cdot \hat{\mathbf{u}} \times \mathbf{w} (\hat{\mathbf{u}} \cdot \mathbf{v})(1 - \cos \theta) \sin \theta + \hat{\mathbf{u}} \times \mathbf{v} \cdot \mathbf{w} \cos \theta \sin \theta \\ &\quad + \hat{\mathbf{u}} \times \mathbf{v} \cdot \hat{\mathbf{u}} (\hat{\mathbf{u}} \cdot \mathbf{w})(1 - \cos \theta) \sin \theta + (\hat{\mathbf{u}} \times \mathbf{v}) \cdot (\hat{\mathbf{u}} \times \mathbf{w}) \sin^2 \theta \end{aligned}$$

Because $\hat{\mathbf{u}}$ is perpendicular to $\hat{\mathbf{u}} \times \mathbf{v}$ and $\hat{\mathbf{u}} \times \mathbf{w}$, we have $\hat{\mathbf{u}} \cdot \hat{\mathbf{u}} \times \mathbf{w} = \mathbf{0}$ and $\hat{\mathbf{u}} \times \mathbf{v} \cdot \hat{\mathbf{u}} = \mathbf{0}$. Also by the triple product identity $\mathbf{v} \cdot \hat{\mathbf{u}} \times \mathbf{w} = \hat{\mathbf{u}} \times \mathbf{w} \cdot \mathbf{v} = \hat{\mathbf{u}} \cdot \mathbf{w} \times \mathbf{v} = -\hat{\mathbf{u}} \cdot \mathbf{v} \times \mathbf{w}$, and $\hat{\mathbf{u}} \times \mathbf{v} \cdot \mathbf{w} = \hat{\mathbf{u}} \cdot \mathbf{v} \times \mathbf{w}$. Hence the terms involving $\sin \theta \cos \theta$ cancel out. Collecting terms a bit we get:

$$R(\theta, \hat{\mathbf{u}})\mathbf{v} \cdot R(\theta, \hat{\mathbf{u}})\mathbf{w} = \mathbf{v} \cdot \mathbf{w} \cos^2 \theta + (\hat{\mathbf{u}} \cdot \mathbf{v})(\hat{\mathbf{u}} \cdot \mathbf{w}) \sin^2 \theta + (\hat{\mathbf{u}} \times \mathbf{v}) \cdot (\hat{\mathbf{u}} \times \mathbf{w}) \sin^2 \theta$$

Using the triple product identity and problem 0 we get

$$(\hat{\mathbf{u}} \times \mathbf{v}) \cdot (\hat{\mathbf{u}} \times \mathbf{w}) = [(\hat{\mathbf{u}} \times \mathbf{v}) \times \hat{\mathbf{u}}] \cdot \mathbf{w} = [-\hat{\mathbf{u}}(\mathbf{v} \cdot \hat{\mathbf{u}}) + \mathbf{v}(\hat{\mathbf{u}} \cdot \hat{\mathbf{u}})] \cdot \mathbf{w} = \mathbf{v} \cdot \mathbf{w} - (\hat{\mathbf{u}} \cdot \mathbf{v})(\hat{\mathbf{u}} \cdot \mathbf{w}).$$

Substituting this into the previous expression we get

$$R(\theta, \hat{\mathbf{u}})\mathbf{v} \cdot R(\theta, \hat{\mathbf{u}})\mathbf{w} = \mathbf{v} \cdot \mathbf{w}(\cos^2 \theta + \sin^2 \theta) = \mathbf{v} \cdot \mathbf{w}.$$

Using problem 0 we can show the following *Jacobi identity* holds:
 $(\mathbf{a} \times \mathbf{b}) \times \mathbf{c} + (\mathbf{c} \times \mathbf{a}) \times \mathbf{b} + (\mathbf{b} \times \mathbf{c}) \times \mathbf{a} = \mathbf{0}$. To see this we compute:

$$\begin{aligned}(\mathbf{a} \times \mathbf{b}) \times \mathbf{c} &= -\mathbf{a}(\mathbf{b} \cdot \mathbf{c}) + \mathbf{b}(\mathbf{a} \cdot \mathbf{c}) \\(\mathbf{c} \times \mathbf{a}) \times \mathbf{b} &= -\mathbf{c}(\mathbf{a} \cdot \mathbf{b}) + \mathbf{a}(\mathbf{c} \cdot \mathbf{b}) \\(\mathbf{b} \times \mathbf{c}) \times \mathbf{a} &= -\mathbf{b}(\mathbf{c} \cdot \mathbf{a}) + \mathbf{c}(\mathbf{b} \cdot \mathbf{a}).\end{aligned}$$

Adding both sides we clearly get a zero vector on the right-hand-side.

Problem 2. Show that $R(\theta, \hat{\mathbf{u}})(\mathbf{v} \times \mathbf{w}) = [R(\theta, \hat{\mathbf{u}})\mathbf{v}] \times [R(\theta, \hat{\mathbf{u}})\mathbf{w}]$.

Solution: As before we directly calculate:

$$\begin{aligned}R(\theta, \hat{\mathbf{u}})\mathbf{v} \times R(\theta, \hat{\mathbf{u}})\mathbf{w} &= [\mathbf{v} \cos \theta + \hat{\mathbf{u}}(\hat{\mathbf{u}} \cdot \mathbf{v})(1 - \cos \theta) + \hat{\mathbf{u}} \times \mathbf{v} \sin \theta] \times [\mathbf{w} \cos \theta + \hat{\mathbf{u}}(\hat{\mathbf{u}} \cdot \mathbf{w})(1 - \cos \theta) + \hat{\mathbf{u}} \times \mathbf{w} \sin \theta] \\&= \mathbf{v} \times \mathbf{w} \cos^2 \theta + (\mathbf{v} \times \hat{\mathbf{u}})(\hat{\mathbf{u}} \cdot \mathbf{w}) \cos \theta (1 - \cos \theta) + \mathbf{v} \times (\hat{\mathbf{u}} \times \mathbf{w}) \cos \theta \sin \theta \\&\quad + (\hat{\mathbf{u}} \times \mathbf{w})(\hat{\mathbf{u}} \cdot \mathbf{v}) \cos \theta (1 - \cos \theta) + \hat{\mathbf{u}} \times \hat{\mathbf{u}}(\hat{\mathbf{u}} \cdot \mathbf{v})(\hat{\mathbf{u}} \cdot \mathbf{w})(1 - \cos \theta)^2 \\&\quad + \hat{\mathbf{u}} \times (\hat{\mathbf{u}} \times \mathbf{w})(\hat{\mathbf{u}} \cdot \mathbf{v})(1 - \cos \theta) \sin \theta + (\hat{\mathbf{u}} \times \mathbf{v}) \times \mathbf{w} \cos \theta \sin \theta \\&\quad + (\hat{\mathbf{u}} \times \mathbf{v}) \times \hat{\mathbf{u}}(\hat{\mathbf{u}} \cdot \mathbf{w})(1 - \cos \theta) \sin \theta + (\hat{\mathbf{u}} \times \mathbf{v}) \times (\hat{\mathbf{u}} \times \mathbf{w}) \sin^2 \theta \\&= [\mathbf{v} \times \mathbf{w} - (\mathbf{v} \times \hat{\mathbf{u}})(\hat{\mathbf{u}} \cdot \mathbf{w}) - (\hat{\mathbf{u}} \times \mathbf{w})(\hat{\mathbf{u}} \cdot \mathbf{v})] \cos^2 \theta + (\hat{\mathbf{u}} \times \mathbf{v}) \times (\hat{\mathbf{u}} \times \mathbf{w}) \sin^2 \theta \\&\quad + [\mathbf{v} \times (\hat{\mathbf{u}} \times \mathbf{w}) - \hat{\mathbf{u}} \times (\hat{\mathbf{u}} \times \mathbf{w})(\hat{\mathbf{u}} \cdot \mathbf{v}) + (\hat{\mathbf{u}} \times \mathbf{v}) \times \mathbf{w} - (\hat{\mathbf{u}} \times \mathbf{v}) \times \hat{\mathbf{u}}(\hat{\mathbf{u}} \cdot \mathbf{w})] \cos \theta \sin \theta \\&\quad + [(\mathbf{v} \times \hat{\mathbf{u}})(\hat{\mathbf{u}} \cdot \mathbf{w}) + (\hat{\mathbf{u}} \times \mathbf{w})(\hat{\mathbf{u}} \cdot \mathbf{v})] \cos \theta \\&\quad + [\hat{\mathbf{u}} \times (\hat{\mathbf{u}} \times \mathbf{w})(\hat{\mathbf{u}} \cdot \mathbf{v}) + (\hat{\mathbf{u}} \times \mathbf{v}) \times \hat{\mathbf{u}}(\hat{\mathbf{u}} \cdot \mathbf{w})] \sin \theta\end{aligned}$$

We must work on each of these terms. The first term is (using problem 0):

$$\begin{aligned}\mathbf{v} \times \mathbf{w} - (\mathbf{v} \times \hat{\mathbf{u}})(\hat{\mathbf{u}} \cdot \mathbf{w}) - (\hat{\mathbf{u}} \times \mathbf{w})(\hat{\mathbf{u}} \cdot \mathbf{v}) &= \mathbf{v} \times \mathbf{w} + [-\mathbf{v}(\mathbf{w} \cdot \hat{\mathbf{u}}) + \mathbf{w}(\mathbf{v} \cdot \hat{\mathbf{u}})] \times \hat{\mathbf{u}} \\&= \mathbf{v} \times \mathbf{w} + [(\mathbf{v} \times \mathbf{w}) \times \hat{\mathbf{u}}] \times \hat{\mathbf{u}} \\&= \mathbf{v} \times \mathbf{w} - (\mathbf{v} \times \mathbf{w})(\hat{\mathbf{u}} \cdot \hat{\mathbf{u}}) + \hat{\mathbf{u}}[(\mathbf{v} \times \mathbf{w}) \cdot \hat{\mathbf{u}}] \\&= \hat{\mathbf{u}}[\hat{\mathbf{u}} \cdot (\mathbf{v} \times \mathbf{w})].\end{aligned}$$

The second term is (using problem 0 and the triple product identity):

$$\begin{aligned}(\hat{\mathbf{u}} \times \mathbf{v}) \times (\hat{\mathbf{u}} \times \mathbf{w}) &= -\hat{\mathbf{u}}[\mathbf{v} \cdot (\hat{\mathbf{u}} \times \mathbf{w})] + \mathbf{v}[\hat{\mathbf{u}} \cdot (\hat{\mathbf{u}} \times \mathbf{w})] = \hat{\mathbf{u}}[\mathbf{v} \cdot (\mathbf{w} \times \hat{\mathbf{u}})] = \hat{\mathbf{u}}[(\mathbf{v} \times \mathbf{w}) \cdot \hat{\mathbf{u}}] \\&= \hat{\mathbf{u}}[\hat{\mathbf{u}} \cdot (\mathbf{v} \times \mathbf{w})].\end{aligned}$$

The third term is (using problem 0 and the Jacobi identity):

$$\begin{aligned}
& \mathbf{v} \times (\hat{\mathbf{u}} \times \mathbf{w}) + (\hat{\mathbf{u}} \times \mathbf{v}) \times \mathbf{w} - \hat{\mathbf{u}} \times (\hat{\mathbf{u}} \times \mathbf{w})(\hat{\mathbf{u}} \cdot \mathbf{v}) - (\hat{\mathbf{u}} \times \mathbf{v}) \times \hat{\mathbf{u}}(\hat{\mathbf{u}} \cdot \mathbf{w}) \\
&= (\mathbf{w} \times \hat{\mathbf{u}}) \times \mathbf{v} + (\hat{\mathbf{u}} \times \mathbf{v}) \times \mathbf{w} + \{\hat{\mathbf{u}} \times [-\mathbf{v}(\hat{\mathbf{u}} \cdot \mathbf{w}) + \mathbf{w}(\hat{\mathbf{u}} \cdot \mathbf{v})]\} \times \hat{\mathbf{u}} \\
&= (\mathbf{w} \times \hat{\mathbf{u}}) \times \mathbf{v} + (\hat{\mathbf{u}} \times \mathbf{v}) \times \mathbf{w} + \{\hat{\mathbf{u}} \times [(\mathbf{v} \times \mathbf{w}) \times \hat{\mathbf{u}}]\} \times \hat{\mathbf{u}} \\
&= (\mathbf{w} \times \hat{\mathbf{u}}) \times \mathbf{v} + (\hat{\mathbf{u}} \times \mathbf{v}) \times \mathbf{w} - \hat{\mathbf{u}}\{[(\mathbf{v} \times \mathbf{w}) \times \hat{\mathbf{u}}] \cdot \hat{\mathbf{u}}\} + [(\mathbf{v} \times \mathbf{w}) \times \hat{\mathbf{u}}](\hat{\mathbf{u}} \cdot \hat{\mathbf{u}}) \\
&= (\mathbf{w} \times \hat{\mathbf{u}}) \times \mathbf{v} + (\hat{\mathbf{u}} \times \mathbf{v}) \times \mathbf{w} + (\mathbf{v} \times \mathbf{w}) \times \hat{\mathbf{u}} \\
&= \mathbf{0}.
\end{aligned}$$

The fourth term is:

$$\begin{aligned}
(\mathbf{v} \times \hat{\mathbf{u}})(\hat{\mathbf{u}} \cdot \mathbf{w}) + (\hat{\mathbf{u}} \times \mathbf{w})(\hat{\mathbf{u}} \cdot \mathbf{v}) &= \hat{\mathbf{u}} \times [-\mathbf{v}(\hat{\mathbf{u}} \cdot \mathbf{w}) + \mathbf{w}(\hat{\mathbf{u}} \cdot \mathbf{v})] = \hat{\mathbf{u}} \times [(\mathbf{v} \times \mathbf{w}) \times \hat{\mathbf{u}}] \\
&= -[(\mathbf{v} \times \mathbf{w}) \times \hat{\mathbf{u}}] \times \hat{\mathbf{u}} \\
&= (\mathbf{v} \times \mathbf{w})(\hat{\mathbf{u}} \cdot \hat{\mathbf{u}}) - \hat{\mathbf{u}}[(\mathbf{v} \times \mathbf{w}) \cdot \hat{\mathbf{u}}] \\
&= \mathbf{v} \times \mathbf{w} - \hat{\mathbf{u}}[\hat{\mathbf{u}} \cdot (\mathbf{v} \times \mathbf{w})].
\end{aligned}$$

The fifth term is:

$$\begin{aligned}
& \hat{\mathbf{u}} \times (\hat{\mathbf{u}} \times \mathbf{w})(\hat{\mathbf{u}} \cdot \mathbf{v}) + (\hat{\mathbf{u}} \times \mathbf{v}) \times \hat{\mathbf{u}}(\hat{\mathbf{u}} \cdot \mathbf{w}) \\
&= [\hat{\mathbf{u}}(\hat{\mathbf{u}} \cdot \mathbf{w}) - \mathbf{w}(\hat{\mathbf{u}} \cdot \hat{\mathbf{u}})](\hat{\mathbf{u}} \cdot \mathbf{v}) + [-\hat{\mathbf{u}}(\hat{\mathbf{u}} \cdot \mathbf{v}) + \mathbf{v}(\hat{\mathbf{u}} \cdot \hat{\mathbf{u}})](\hat{\mathbf{u}} \cdot \mathbf{w}) \\
&= -\mathbf{w}(\hat{\mathbf{u}} \cdot \mathbf{v}) + \mathbf{v}(\hat{\mathbf{u}} \cdot \mathbf{w}) \\
&= (\mathbf{w} \times \mathbf{v}) \times \hat{\mathbf{u}} \\
&= \hat{\mathbf{u}} \times (\mathbf{v} \times \mathbf{w}).
\end{aligned}$$

Plugging all these expressions in we get:

$$\begin{aligned}
R(\theta, \hat{\mathbf{u}})\mathbf{v} \times R(\theta, \hat{\mathbf{u}})\mathbf{w} \\
&= \hat{\mathbf{u}}[\hat{\mathbf{u}} \cdot (\mathbf{v} \times \mathbf{w})] + \{\mathbf{v} \times \mathbf{w} - \hat{\mathbf{u}}[\hat{\mathbf{u}} \cdot (\mathbf{v} \times \mathbf{w})]\} \cos \theta + \hat{\mathbf{u}} \times (\mathbf{v} \times \mathbf{w}) \sin \theta \\
&= R(\theta, \hat{\mathbf{u}})(\mathbf{v} \times \mathbf{w}).
\end{aligned}$$